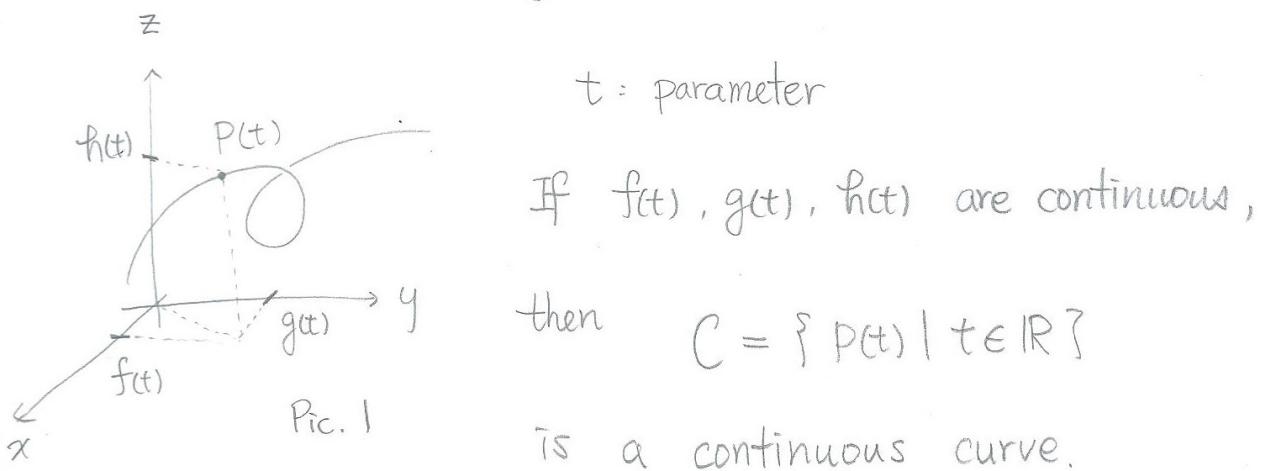


## § Curves and their tangents

Let  $t \in \mathbb{R}$  be time variable. For each  $t$ , we can define a position function in  $\mathbb{R}^3$ :

$$P(t) = (f(t), g(t), h(t)) \quad \text{See . Pic. 1.}$$



Again, for each curve  $C \subset \mathbb{R}^3$ , the choice of parametrization is not unique.

Define  $\vec{v}(t) = (f'(t), g'(t), h'(t))$  to be the velocity of  $P$ .  
(tangent vector)

$$|\vec{v}|(t) = |\vec{v}(t)| \text{ to be the speed of } P.$$

By fundamental theorem of calculus:

$$P(0) + \int_0^t \vec{v}(t) dt = P(t) : \text{position at time } t.$$

$$\text{where } \int_0^t \vec{v}(t) dt = \int_0^t (f'(t), g'(t), h'(t)) dt$$

P2.

$$= \left( \int_0^t f'(t) dt, \int_0^t g'(t) dt, \int_0^t h'(t) dt \right).$$

Generally, we call the type of function  $\{P(t)\}$  a vector value function. It will satisfy the following properties:

Properties:

- $(r(t) \cdot \vec{v}(t))' = r'(t) \cdot \vec{v}(t) + r(t)(\vec{v}'(t))$

where  $r(t)$  is a scalar function.

- (Linearity).  $(\vec{v} + c\vec{w})' = \vec{v}' + c\vec{w}'$

for any two vector value function

$\vec{v}, \vec{w}$  and  $c \in \mathbb{R}$ .

- (Dot product)  $(\vec{u} \cdot \vec{v})' = \vec{u}' \cdot \vec{v} + \vec{u} \cdot \vec{v}'$

- (Cross product)  $(\vec{u} \times \vec{v})' = \vec{u}' \times \vec{v} + \vec{u} \times \vec{v}'$

- (Chain rule):

$$(\vec{u}(r(t)))' = \frac{d}{dt}(\vec{u}(r(t))) = r'(t) \vec{u}'(r(t))$$

Arc length along a space curve:

Let  $r(t) = (x(t), y(t), z(t))$

then the arc length from  $r(a)$  to  $r(b)$  is

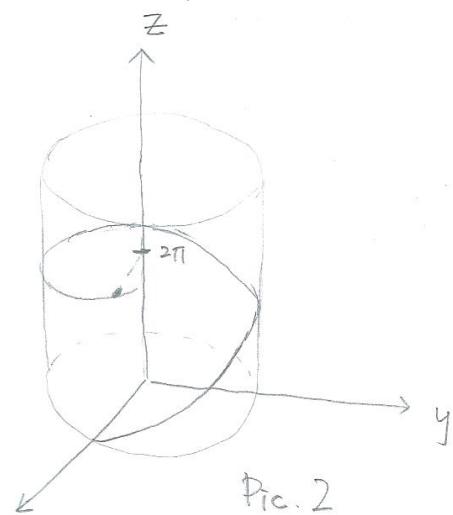
$$L_{ab} = \int_a^b |r'(t)| dt.$$

Example: (Helix)

$$\mathbf{r}(t) = (\cos t, \sin t, t)$$

The arc length of  $C = \{\mathbf{r}(t)\}$  from  $\mathbf{r}(0)$  to  $\mathbf{r}(2\pi)$  is

$$\begin{aligned} L_{0,2\pi} &= \int_0^{2\pi} |\mathbf{r}'(t)| dt = \int_0^{2\pi} [(-\sin)^2(t) + \cos^2 t + 1]^{1/2} dt \\ &= \int_0^{2\pi} \sqrt{2} dt = 2\sqrt{2}\pi \end{aligned}$$



Pic. 2

Rmk : If we regard  $\mathbf{r}(t)$  to be the position function of a particle, then  $|\mathbf{r}'(t)|$  is the speed. The arc length integral of  $|\mathbf{r}'(t)|$ .

- Recall that the parametrizations of a curve is not unique. We can always choose one that  $|\mathbf{r}'(t)| \equiv 1$ . In this case, the arc length

$$L_{ab} = \int_a^b 1 dt = |b-a|.$$

Curvature: Consider a plane curve  $\mathbf{r}(t) = (x(t), y(t))$ , with  $|\mathbf{r}'(t)| = 1$ . Then we define

$$K(t) = |\mathbf{r}''(t)|$$

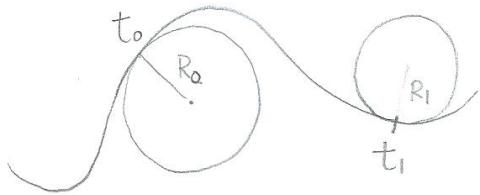
P4.

Never forget the condition  $|r'(t)| = 1$ .

Geometric meaning:  $K = \frac{1}{R}$ , where  $R$  is the radius of the approximation circle (circle of curvature, osculating circle)

See Pic 3.

Pf:



Pic 3.

Let  $C = \{C(t)\}$  be the osculating circle with

$$\begin{cases} |C'(t_0)| = 1 = |r'(t_0)| \\ |C''(t_0)| = K = |r''(t_0)| \end{cases}$$

$$C(t_0) = r(t_0) \quad \text{for some } t_0.$$

Since  $C(t)$  is a circle, we can take

$$C(t) = (R \cos(\alpha t + \beta) + P_1, R \sin(\alpha t + \beta) + P_2)$$

$$\begin{aligned} \text{Now, } |C'(t_0)| = 1 &\Rightarrow [\alpha^2 R^2 \sin^2(\alpha t_0 + \beta)^2 + \alpha^2 R^2 \cos^2(\alpha t_0 + \beta)^2]^{1/2} \\ &= |\alpha| |R| = 1 \quad ; \quad |\alpha| = \frac{1}{R} \end{aligned}$$

$$\begin{aligned} \therefore |C''(t_0)| &= [\alpha^4 R^2 \cos^2(\alpha t_0 + \beta)^2 + \alpha^4 R^2 \sin^2(\alpha t_0 + \beta)^2]^{1/2} \\ &= |\alpha^2 R| = \frac{1}{R}. \end{aligned}$$

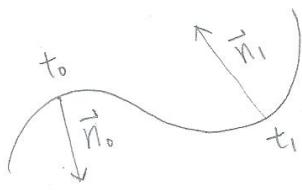
In particular, the curvature of a circle of radius  $R$  is a constant function  $K = \frac{1}{R}$ . P5.

Normal vector: For a plane curve  $r(t) = (x(t), y(t))$ , with  $|r'(t)| = 1$ , we have

$$\begin{aligned}\frac{d}{dt} |r'(t)|^2 &= \frac{d}{dt} (r'(t) \cdot r'(t)) \\ &= 2 r''(t) \cdot r'(t) = 0\end{aligned}$$

$$\therefore r''(t) \perp r'(t)$$

So we call  $\vec{n} = \frac{r''(t)}{|r''(t)|}$  the Principal unit normal of  $r(t)$ .  
see. Pic.4

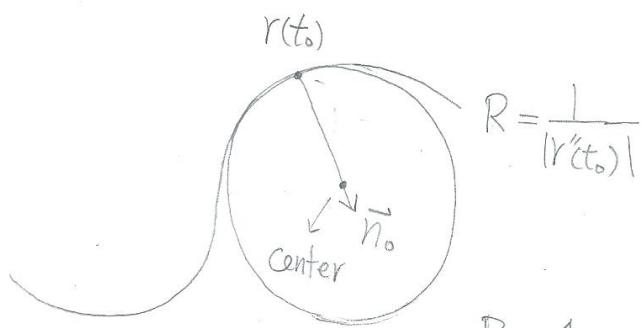


Now, the center of the osculating circle is on  $\{r(t_0) + s \cdot \vec{n}_0, \text{ for } s > 0\}$   
So we can write down the eq:

$$C_{t_0} = \left\{ \left( \underbrace{\frac{1}{|r''(t_0)|} \cos(t), \frac{1}{|r''(t_0)|} \sin(t)}_m \right) + r(t_0) + \underbrace{\frac{r''(t_0)}{|r''(t_0)|^2}}_R \right\}$$

See. Pic.4

center.

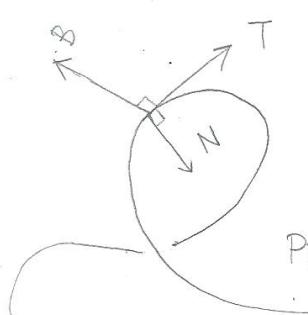


Pic. 4

Space curve : Normal & Binormal :

Let  $r(t) = (x(t), y(t), z(t))$  be a space curve, with  $|r'(t)| = 1$ . We have  $T := r'(t)$  : tangent vector  
 $N := \frac{r''(t)}{|r''(t)|}$  : normal vector.

Define:  $B := T \times N$  to be the Binormal vector see Pic. 5

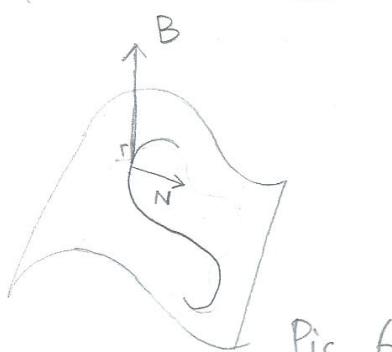


Pic. 5

$$\left\{ \begin{array}{l} B \perp T \\ N \perp T \\ B \perp N \end{array} \right.$$

Geometrically, if we have a plane curve on a sheet of paper.

$N$  will be on this paper and  $B$  will be perpendicular to this paper.  
See Pic. 6



Pic. 6

Acceleration: Let  $r(t) = (x(t), y(t), z(t))$  (Now we don't have  $|r'(t)| = 1$ )  
 Recall that  $\vec{v} = \frac{dr}{dt}$  : velocity

Change the parameter  $t \rightarrow s$  s.t  $|r(s)| = 1$ , we have

$$T = \frac{dr}{ds} \begin{matrix} \text{unit} \\ \text{tangent vector} \end{matrix}$$

Acceleration:

Chain rule

$$\begin{aligned}\vec{a} &= \frac{d}{dt}(\vec{v}) = \frac{d}{dt}\left(\frac{dr}{ds} \cdot \frac{ds}{dt}\right) = \frac{d}{dt}(T \cdot \frac{ds}{dt}) \\ &= \frac{d^2s}{dt^2} \cdot T + \frac{dT}{dt} \cdot \frac{ds}{dt} \\ &= \frac{d^2s}{dt^2} \cdot T + \frac{dT}{ds} \left(\frac{ds}{dt}\right)^2 \\ &= \frac{d^2s}{dt^2} \cdot T + \left(\frac{ds}{dt}\right)^2 \cdot KN \\ &= a_T T + a_N N\end{aligned}$$

where  $\begin{cases} a_T = \frac{d^2s}{dt^2} & \text{tangent scalar component of } \vec{a} \\ a_N = \left(\frac{ds}{dt}\right)^2 \cdot K & \text{normal scalar component of } \vec{a} \end{cases}$

No Binormal component.

How to find the parameter  $s$  s.t.  $|r'(s)| = 1$  ?

Suppose we have  $r(t) = (x(t), y(t), z(t))$ .

let  $t = t(s)$ .

$$\left| \frac{d}{ds}(r(t(s))) \right| = \left| (x'(t) \cdot t'(s), y'(t) \cdot t'(s), z'(t) \cdot t'(s)) \right| \\ = |t'(s) \cdot r'(t)| = 1$$

$$\text{so } t'(s) = \frac{1}{|r'(t)|} = \frac{dt}{ds}$$

$$\Rightarrow \frac{ds}{dt} = |r'(t)|, \text{ take } s = \int_0^t |r'(t)| dt,$$

We have the parameter for  $s$ .

Namely, we should parametrize a curve by its arclength.